Feature Visualization

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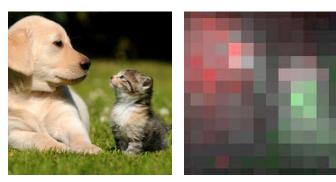
21.06.2018

Feature Visualization

How neural networks build up their understanding of images

Olah, et al., "Feature Visualization", Distill, 2017. [3]

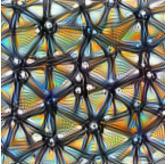
Attribution



What parts are responsible for the activation?

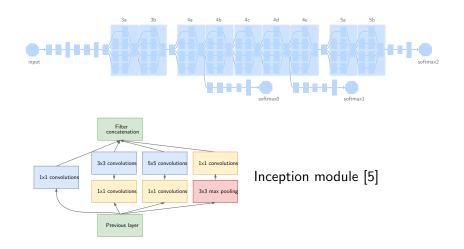
Feature Visualization





What kind of image does the neuron/layer activate for?

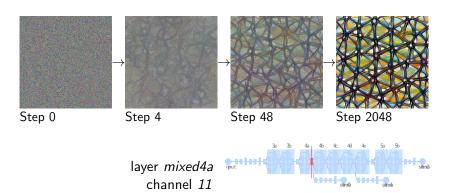
Network Architecture (GoogLeNet)



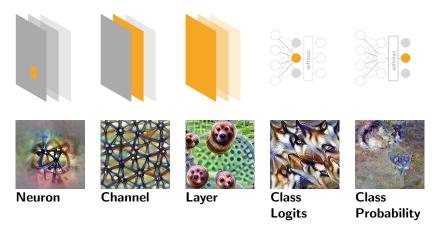
Feature Visualization by Optimization

- Freeze parameters of trained model
- ▶ Update image X using the gradients $\nabla_X \mathcal{L}$ to optimize an objective \mathcal{L} :

$$X += \lambda \nabla_X \mathcal{L}$$



What to visualize



There are a lot of different parts of a network that we might want to interpret, for which we need different objective functions.

For a neuron



The idea is to maximize the activation z_{lcxy} of a given neuron:

$$\mathcal{L}_{lcxy} = z_{lcxy}$$

I: layer index

c: channel index

x,y: spatial position



For a negative optimization, the output of the pre-activation \hat{z}_{lcxy} can be taken for the gradient to be non-zero in case of a ReLU.

For a channel



Extending the neuron objective to a channel, following objective can be used:

$$\mathcal{L}_{\mathit{lc}} = rac{1}{w*h} \sum_{x,y} z_{\mathit{lcxy}}$$
 w : layer width h : layer height



This objective leads to a repetitive occurance of the pattern.

For a layer



A layer captures many patterns, so it's difficult to find a good objective.

One approach to this is the Deep Dream objective which aims to maximize what the layer deems 'interesting':

$$\mathcal{L}_I = \|z_I\|^2$$

For a class label











post-softmax[k]

For the class labels, there are two possibilities:

Optimizing the pre-softmax activation (evidence of the class k):

 $\mathcal{L}_{I} = \hat{z}_{Ik}$

k: class index

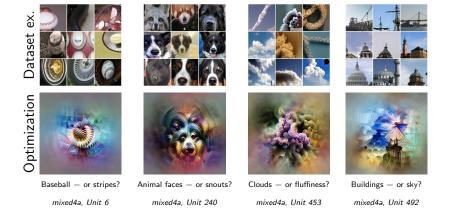
L: output layer

Or optimizing the post-softmax activation (probability of the class k, given the evidence):

$$\mathcal{L}_L = z_{Lk}$$

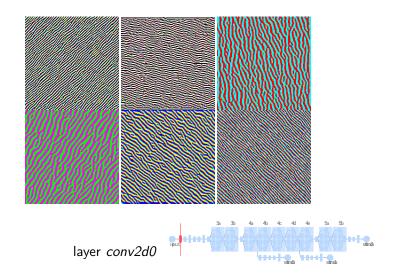
Why Optimization?

Dataset examples vs. optimization

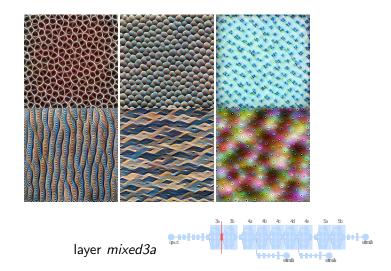


Although dataset examples give a good intuition about what a neuron activates for, it might not show the full picture.

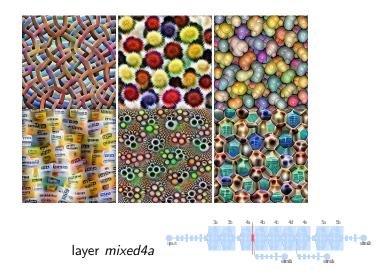
Edges



Textures



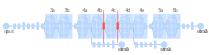
Patterns



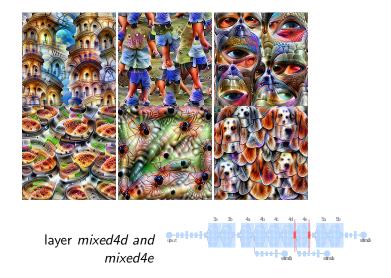
Parts



layer mixed4b and mixed4c

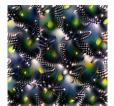


Examples Objects



Diversity

Motivation



Negative optimized



Minimum activation examples



Slightly negative activation examples



Slightly positive activation examples



Positive optimized



Maximum activation examples

Does the optimized image show the "facets" of activation?

Diversity Approaches

- "Intra-class" diversity, optimizing for the cluster centroids
- Use diverse dataset examples as starting point
- ▶ Generative model → pick diverse samples
- Optimize with diversity term

Diversity

Optimization with diversity term

Gram matrix G:

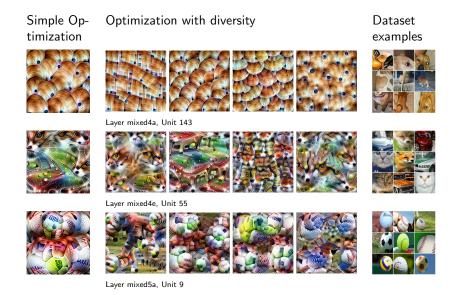
$$G_{i,j} = layer_n[:,:,i] \cdot layer_n[:,:,j]$$

Diversity term as negative pairwise cosine similarity:

$$C_{diversity} = -\sum_{a} \sum_{a \neq b} \frac{vec(G_a) \cdot vec(G_b)}{\|vec(G_a)\| \|vec(G_b)\|}$$

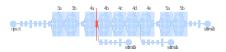
Optimize jointly for optimization objective and diversity term:

$$\mathcal{L} += C_{diversity}$$

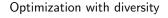




In contrast to the simple optimization which suggests the channel activation on top of a dogs head through the curved fur and eyes, the diverse examples show that the channel also reacts to just the brown fur texture.



Simple Optimization



Dataset examples







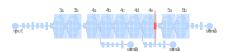






Layer mixed4e, Unit 55

This channel activating for cats, foxes and cars shows that for a better understanding we may also need to examine combinations of neurons.



Simple Optimization

Optimization with diversity











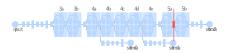




Layer mixed5a, Unit 9

The expectation of optimization with diversity might be images with different kinds of balls, like in the dataset examples.

This example shows that the diversity term can also be misleading, because it pushes images to be different from each other, introducing features that are not relevant to the objective.



Interaction between Neurons

If single channels are the basis directions of the activation space of a layer, this can be extended to the activation direction

$$d_I = \begin{bmatrix} z_{I0} & z_{I1} & \dots & z_{IC} \end{bmatrix}^T$$

The objective for a given layer I and direction d_I is

$$\mathcal{L}_{I} = \frac{1}{whC} \sum_{x,y,c} z_{lcxy} d_{lc}$$

Random directions have been found to seem as interpretable as basis directions. [6]

Basic directions have been found to be interpretable more often than random directions. [1]

Interaction between Neurons

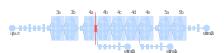
Interpolation

Given two channels, their base directions can be interpolated by

$$d_{l,t} = (1-t)d_{lc_1} + td_{lc_2}$$

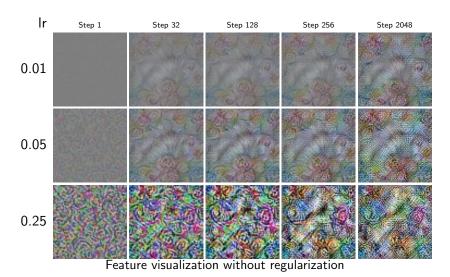


channel 476 channel 460



The Enemy of Feature Visualization

How to make visualizations look good



The Enemy of Feature Visualization

How to make visualizations look good



Feature visualization without regularization

When optimized without regularization, high frequency patterns emerge to activate the neuron.

While it is not fully understood, the patterns seem to be caused by strided convolutions and pooling operations, creating a high frequency grid pattern in the gradient.

The Spectrum of Regularization

To make generated images more natural looking, a range of regularization techniques can be applied:

Weak Regularization

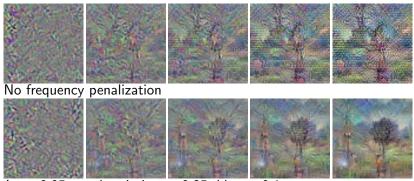
- ► Frequency penalization
- Transformation robustness

Strong Regularization

- Learned priors
- Dataset examples

Regularization

Frequency penalization



 L_1 : -0.05, total variation: -0.25, blur: -0.1

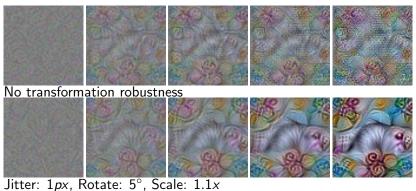
Total variance penalizes variance between neighboring pixels.

Blurring implicitely penalizes high-frequency noise.

These approaches also discourage legitimate high-frequency patterns like edges.

Regularization

Transformation robustness



Using transformation robustness as regularizer leads to images that still activate the target even if they're slightly transformed.

Regularization

Learned prior

Another step to creating natural looking images is to train a model of the real data and try to enforce it.

This approach can produce photorealistic visualizations [2], but it's not necessarily clear what came from the visualization objective and what came from the prior.

Preconditioning and Parameterization

Another way to improve visual quality is to "precondition" the image.

The preconditioner chosen here is a transformation g to the fourier basis and a color decorrelation h using a Cholesky decomposition from the training set.

Instead of using the image X directly, the transformed image $\tilde{X} = h(g(X))$ is used as input for the network.

Preconditioning and Parameterization

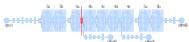


Resulting visualizations in decorrelated space seem to have better visual quality and develop faster. (Ir = 0.05; with transformation robustness)

Optimization initialized with example

Visualization of mixed4a, channel 240, initialized with a picture fitting to the neuron. The snout stays the same during optimization while the non related parts get more high frequency patterns. (no regularization used)





Conclusion

- Basics of feature visualization and optimization objectives
- How do we get diversity in feature visualization?
- Improving the visual quality of generated examples
- \rightarrow There's a lot of room for more research.

Follow-up paper: Olah, et al., "The Building Blocks of Interpretability", Distill, 2018.[4]

- [1] D. Bau, B. Zhou, A. Khosla, A. Oliva, and A. Torralba. Network dissection: Quantifying interpretability of deep visual representations. 2017.
- [2] A. Nguyen, A. Dosovitskiy, T. Yosinski, Jason band Brox, and J. Clune. Synthesizing the preferred inputs for neurons in neural networks via deep generator networks. NIPS 29, 2016.
- [3] C. Olah, A. Mordvintsev, and L. Schubert. Feature visualization. *Distill*, 2017. https://distill.pub/2017/feature-visualization.
- [4] C. Olah, A. Satyanarayan, I. Johnson, S. Carter, L. Schubert, K. Ye, and A. Mordvintsev. The building blocks of interpretability. *Distill*, 2018. https://distill.pub/2018/building-blocks.
- [5] C. Szegedy, W. Liu, Y. Jia, P. Sermanet, S. Reed, D. Anguelov, D. Erhan, V. Vanhoucke, and A. Rabinovich. Going deeper with convolutions. *Proceedings* of the IEEE conference on computer vision and pattern recognition, pages 1–9, 2015. arXiv:1409.4842.
- [6] C. Szegedy, W. Zaremba, I. Sutskever, J. Bruna, D. Erhan, I. Goodfellow, and R. Fergus. Intriguing properties of neural networks. arXiv preprint, 2013. arXiv:1312.6199.

Thank you!