AlphaGo Zero & AlphaZero

Mastering Go, Chess and Shogi without human knowledge

Silver et al. 2017-2018

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Outline

- Timeline
- AlphaGo Zero
 - Training Pipeline
 - Modified MCTS
 - Reasons for better performance
- AlphaZero
 - Generalization to Chess/Shogi
 - AlphaZero vs Stockfish
- Conclusion

- 2012: Crazy Stone
 - MCTS search with handcrafted heuristic
 - Professional level play
- 2015: AlphaGo Fan
 - MCTS with Value and Policy Network
 - Defeated European Go champion Fan Hui (2-dan)
- 2016: AlphaGo Lee
 - Larger networks than AlphaGo Fan
 - Added selfplay of policy network
 - Won 3/1 against Lee Sedol (9-dan)
- 2017: AlphaGo Master
 - Use single network for both policy and value
 - Using ResNet instead of Convolutional NN
 - Won 60/0 against team of professional players
- 2018 AlphaGo Zero
 - Trained from scratch
- 2018 AlphaZero
 - Generalized to Chess & Shogi





AlphaGo Zero: learning from scratch

- No human knowledge
 - Trained by self-play reinforcement learning from scratch
 - Only raw board as input
- Single neural network
 - Policy and value networks are combined into single NN
- Simpler (cheaper) search during gameplay
 - Instead of Monte-Carlo rollouts, only uses NN to evaluate

Less complex and more general => AlphaZero (also plays Chess, Shogi, ...)

Learning Pipeline



Learning Pipeline



Policy/Value-Network



p_i

Learning Pipeline



Modified MCTS



Select



Select action according to PUCT

$$U(s,a) = c_{puct} P(s,a) \frac{\sqrt{\sum_{b} N(s,b)}}{1+N(s,a)}$$

$$a_t = \operatorname*{argmax}(Q(s_t,a) + U(s_t,a))$$

$$c_{puct} : \text{level of exploaration}$$

Expand

• Evaluate NN at leaf node:



Backup



• Increment visit counts

$$N(s_t, a_t) = N(s_t, a_t) + 1$$

- Add value to action value $W(s_t, a_t) = W(s_t, a_t) + v$
- Update Mean action value

$$Q(s_t, a_t) = \frac{W(s_t, a_t)}{N(s_t, a_t)}$$

Play



$$\pi(a|s_t) = \frac{N(s_t, a)^{1/\tau}}{\sum_b N(s_t, b)^{1/\tau}}$$

Policy iteration





- $(\mathbf{p},\mathbf{v}) = \mathbf{f}_{\theta}(s)$ **p** : policy
- π : MCTS probabilities
- z: outcome of game

Why is it better?

- MCTS search in training loop provides stable gradient for training
 - Augmented policy is always better at predicting the best move

Supervised vs Reinforcement learning



Why is it better?

- MCTS search in training loop provides stable gradient for training
 - Augmented policy is always better at predicting the best move
- ResNets instead of ConvNets
 - Ability to train even deeper models
- Same network for Policy and Value
 - Multi-task learning with hard parameter sharing regularizes training and prevents overfitting



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Comparison to human play

- Superhuman performance
- Learned to play human Joseki



Pincer 3-3 point

70

AlphaGo Zero vs AlphaZero

- Absence of human knowledge made transfer to Shogi and Chess very easy
- No change to NN architecture
- Only raw board states as input
- No evaluator → Continuous update of NN

Go vs Chess/Shogi

Rules	Go	Chess/Shogi
Translation invariance	Yes	Partial
Locality	Yes	No
Symmetry	Yes	No
Action space	Simple	Compound
Game outcomes	Probability of winning	Win / Loss / Draw

Performance of AlphaZero



AlphaZero vs Stockfish

- Stockfish: Alpha Beta Pruning with handcrafted heuristics, endplay-tables, opening book, etc...
- Stockfish 60'000'000 Moves/Second
- AlphaZero 60'000 Moves/Second

AlphaZero vs. Stockfish



W: 29.0% D: 70.6% L: 0.4%

Conclusion

- Playing smart is better than brute-force
- Generality is better than handcrafting features
- Not injecting human knowledge promotes generality
- Multitask learning prevents overfitting

References

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