

HINT: Hierarchical Invertible Neural Transport for Density Estimation and Bayesian Inference

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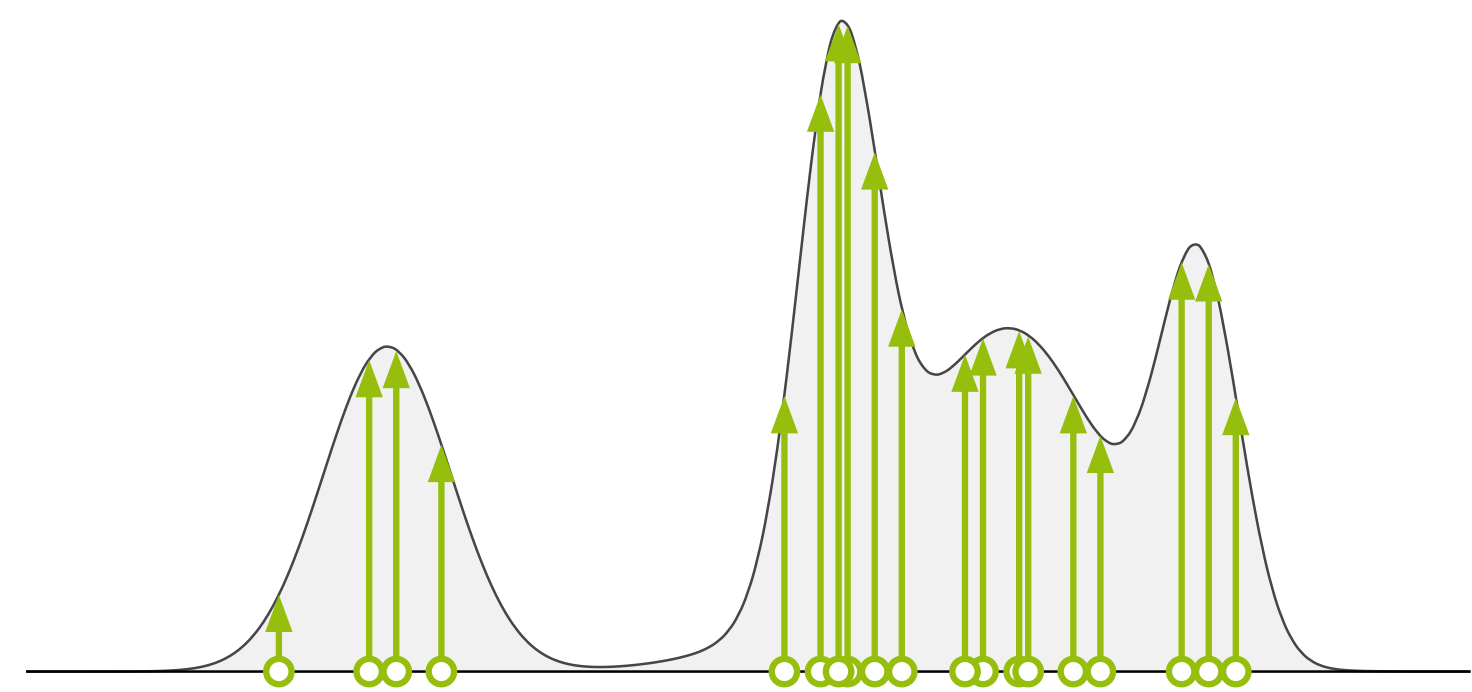
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Density Estimation

Given a sample of data points \mathbf{x} that all stem from the same, unknown source distribution $p^*(\mathbf{x})$,

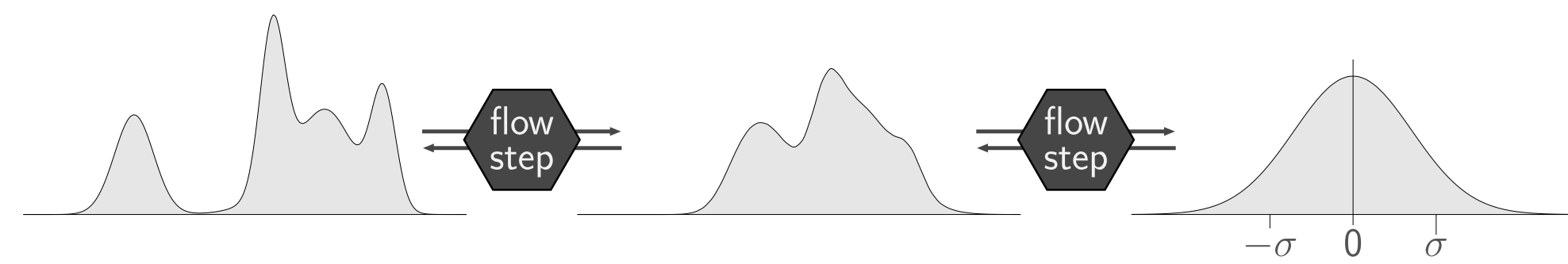


model the underlying density $p(\mathbf{x})$ to gain insights into the data \mathbf{x} or generate new samples:



Transport and Normalizing Flow

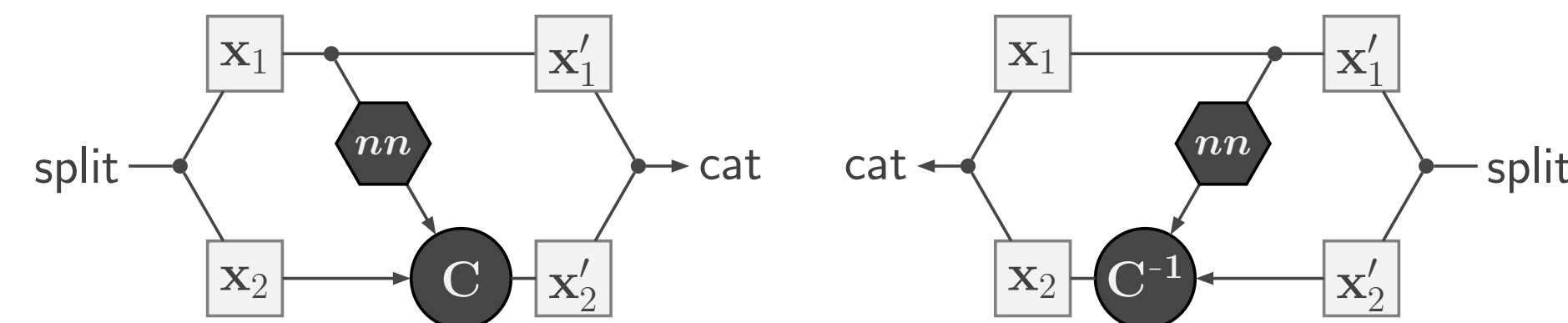
► **Transport** bijective mapping between probability densities



► **Normalizing Flow** transport from $p(\mathbf{x})$ to standard normal latent distribution $\mathcal{N}(\mathbf{z}; \mathbf{0}, \mathbf{I})$ as a sequence of neural steps [1]

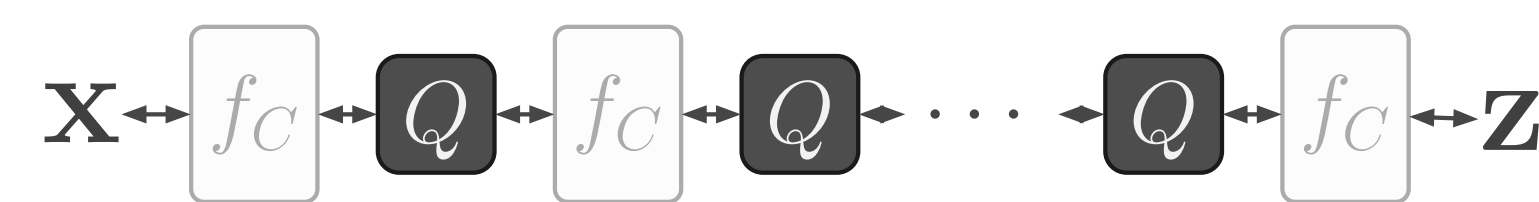
$$\mathcal{L}(\mathbf{x}) = \frac{1}{2} \|\mathbf{T}(\mathbf{x})\|_2^2 - \log |\mathbf{J}_T(\mathbf{x})|$$

► **Split Coupling** fast inversion and Jacobian determinant [2]

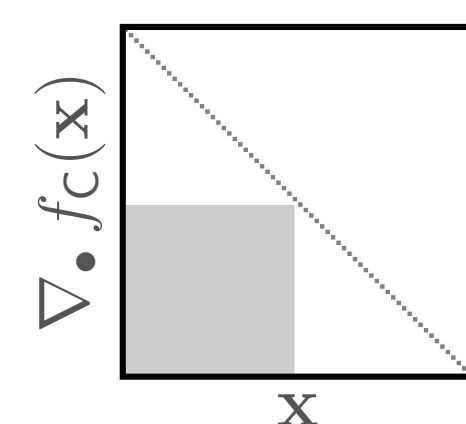


► **Affine Coupling** take $\mathbf{C} = \mathbf{x}_2 \odot \exp(\text{nn}_s(\mathbf{x}_1)) + \text{nn}_t(\mathbf{x}_1)$ [3]

► **Varying Splits** ensured by orthogonal matrices, $\mathbf{Q}^{-1} = \mathbf{Q}^\top$

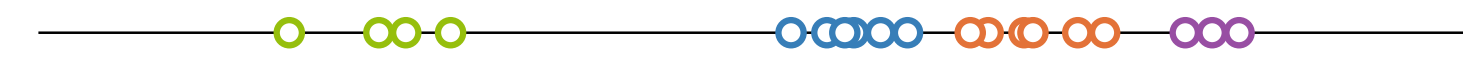


► **Jacobian Matrix** lower triangular [3], but **high sparsity means reduced expressive power** because many variable interactions are not modelled

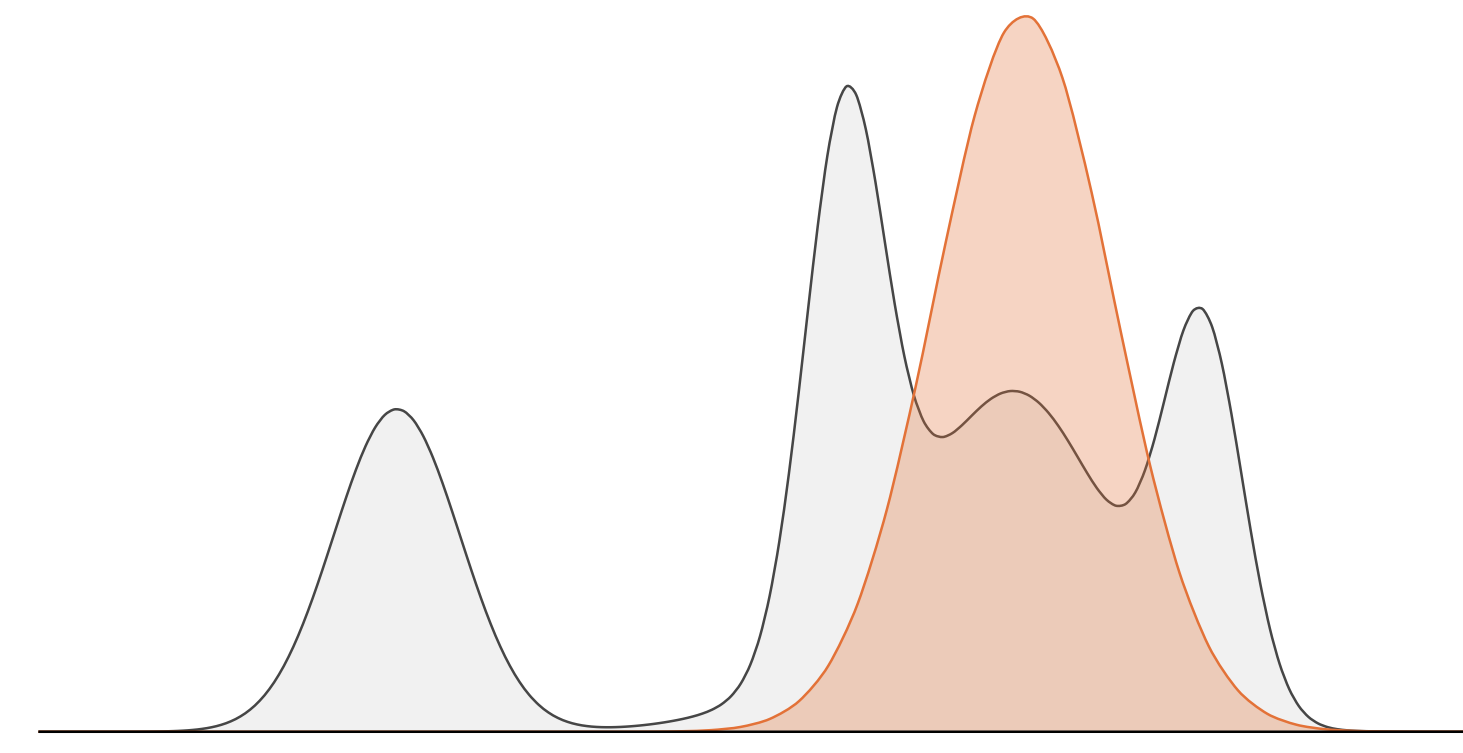


Bayesian Inference

Given a sample of data points \mathbf{x} with potentially ambiguous and uncertain attributes \mathbf{y} , in this example their color,



model the posterior density $p(\mathbf{x} | \mathbf{y})$ of data \mathbf{x} given a partial observation \mathbf{y} , in this example $p(\mathbf{x} | \mathbf{y} = \text{orange})$:



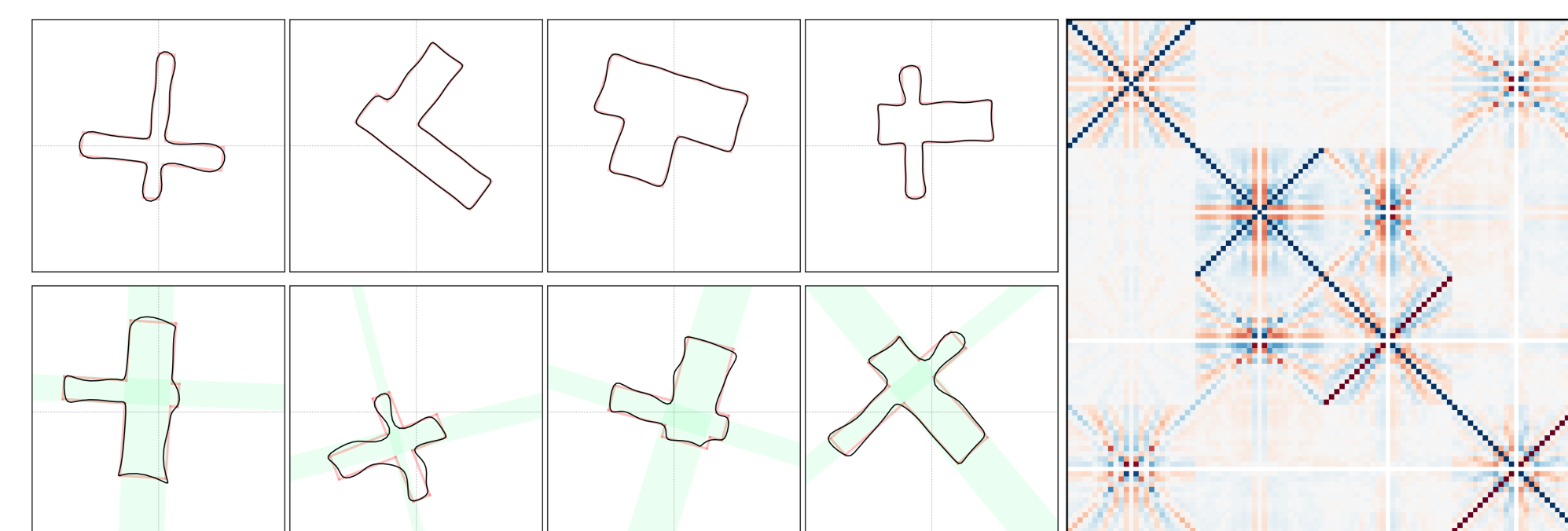
Fourier Curve Data Set

We can parameterize a closed 2d curve in terms of $2M + 1$ complex, 2d Fourier coefficients \mathbf{a}_m , based on a set of points \mathbf{p}_n :



$$\mathbf{g}(t) = \sum_{m=-M}^M \mathbf{a}_m \cdot e^{2\pi i \cdot m \cdot t} \quad [5]$$

- **flexible** number of dimensions and **easy to scale up**
- **complicated correlation** structure between dimensions
- exact ground truth and **quantitative metrics** for samples
- natural **representation in 2d** enables visual inspection

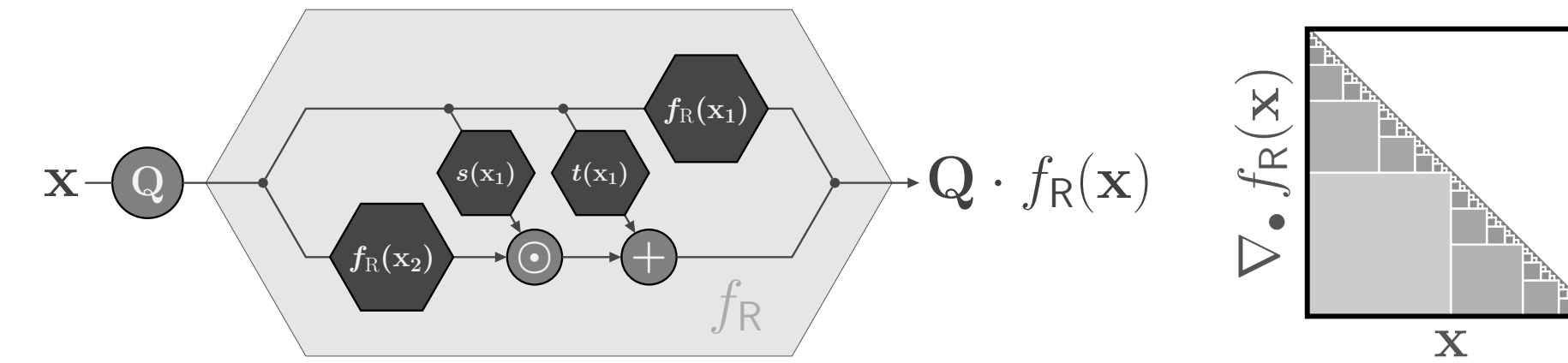


Cross shapes with random angles, bar lengths/widths/shifts and positions; parameterized by vectors $\mathbf{a} \in \mathbb{C}^{25 \times 2} \rightarrow \mathbf{x} \in \mathbb{R}^{100}$

Recursive Coupling

We extend the split coupling design by making it recursive:

► **Recursion** one sub-block for each lane in a block



► **Stopping Criterion** when no further splits are possible

$$f_{R,k}(\mathbf{x}) = \begin{cases} f_C(\mathbf{x}), & \text{if } N_k \leq 3, \\ \begin{bmatrix} f_{R,k-1}(\mathbf{x}_1) \\ C_k(f_{R,k-1}(\mathbf{x}_2) | \mathbf{x}_1) \end{bmatrix} & \text{otherwise} \end{cases}$$

► **Jacobian Matrix** becomes **dense lower triangular**

► **Train Loss** no change, $\log |\mathbf{J}_T(\mathbf{x})| = \sum$ all diagonal entries

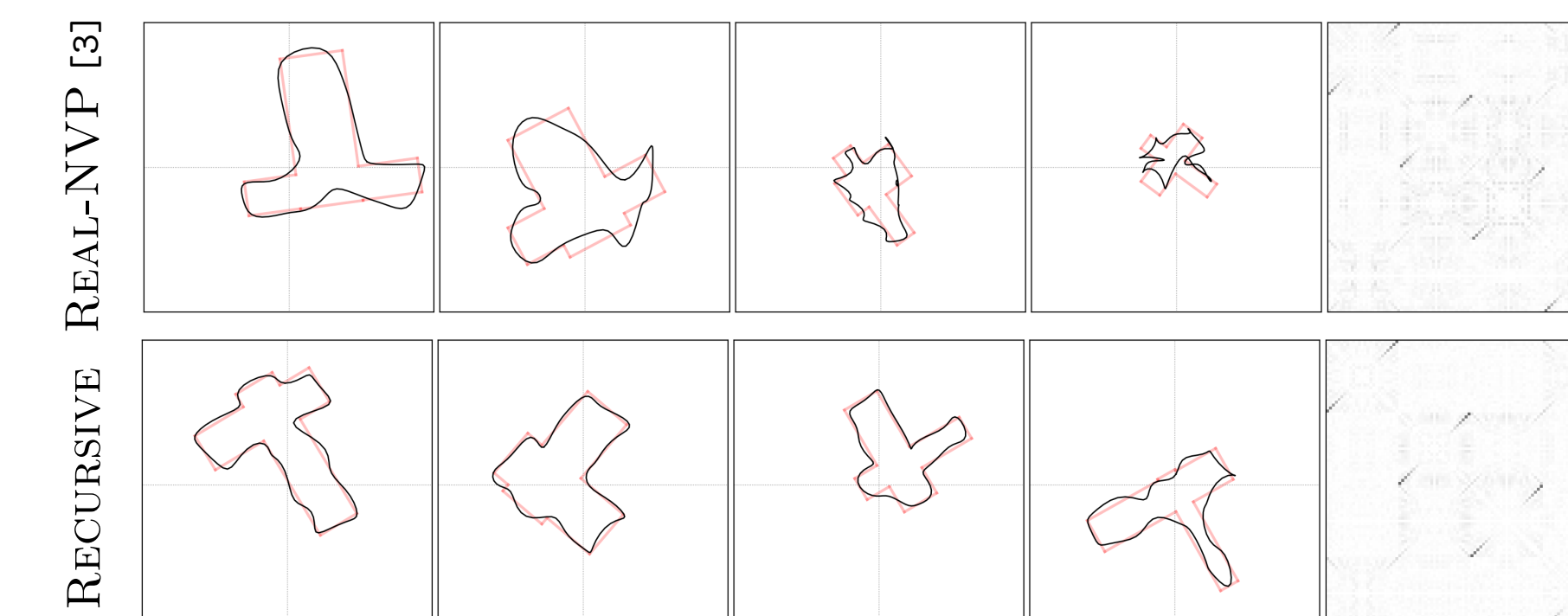
► **Complexity** number of OPs decreases with recursion depth, all subnetworks within one block can be evaluated in parallel

► **Results On UCI Benchmarks** [4] normal REAL-NVP [3] versus our RECURSIVE model at equal parameter budget, in terms of *log-likelihood* on test set (higher is better)

BLOCKS		DIM	REAL-NVP [3]	RECURSIVE
4	POWER	6	-0.054 ± 0.017	-0.027 ± 0.018
	GAS	8	7.620 ± 0.136	7.662 ± 0.094
	MINIBOONE	42	-19.296 ± 0.395	-14.547 ± 0.164
8	POWER	6	0.093 ± 0.002	0.080 ± 0.007
	GAS	8	8.062 ± 0.177	8.137 ± 0.055
	MINIBOONE	42	-16.625 ± 0.119	-14.117 ± 0.163

→ positive effect of recursion **increases with higher DIM**

► **Results On Fourier Curve Data Set** generated samples and error in \mathbf{x} correlation matrices (more white is better):



Quantitative results in terms of *log-likelihood*, *intersection-over-union* and average *Hausdorff distance*:

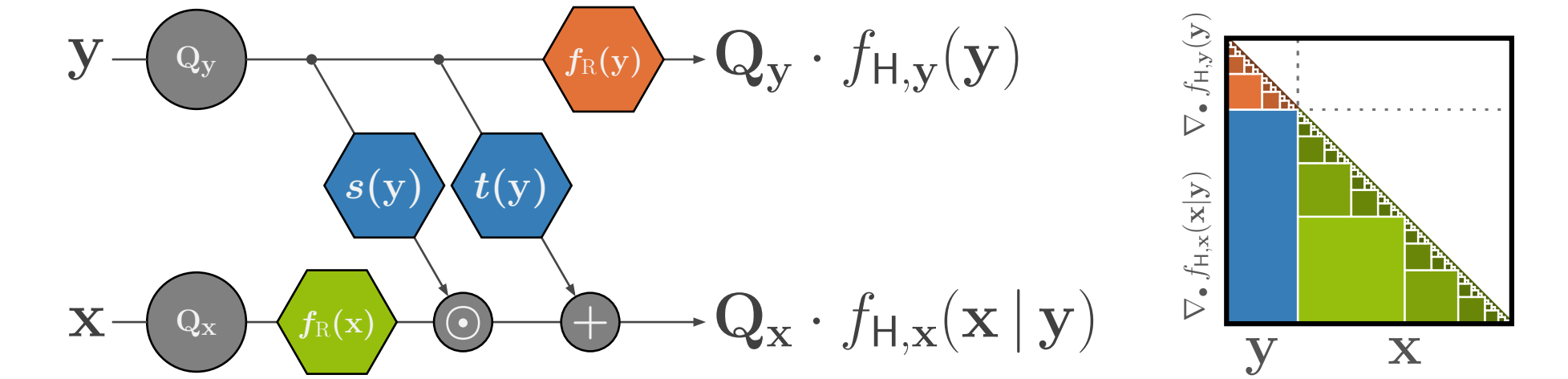
BLOCKS	4x RNVP [3]	4x REC	8x RNVP [3]	8x REC
LL ↑	3.419	3.627	3.329	3.637
IoU ↑	0.594	0.823	0.588	0.823
H-DIST ↓	0.134	0.077	0.138	0.073

→ **Recursive design works better in all 3 metrics**

Hierarchical Architecture – HINT

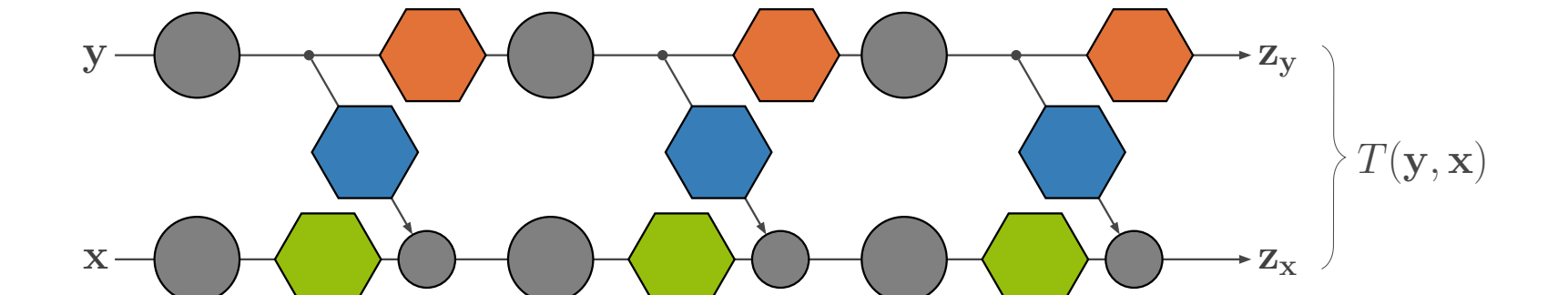
For paired data \mathbf{x} and observations \mathbf{y} , the top level split in the recursion can represent their separation:

► **Dependency** of \mathbf{x} -lane on \mathbf{y} -lane, but not vice versa



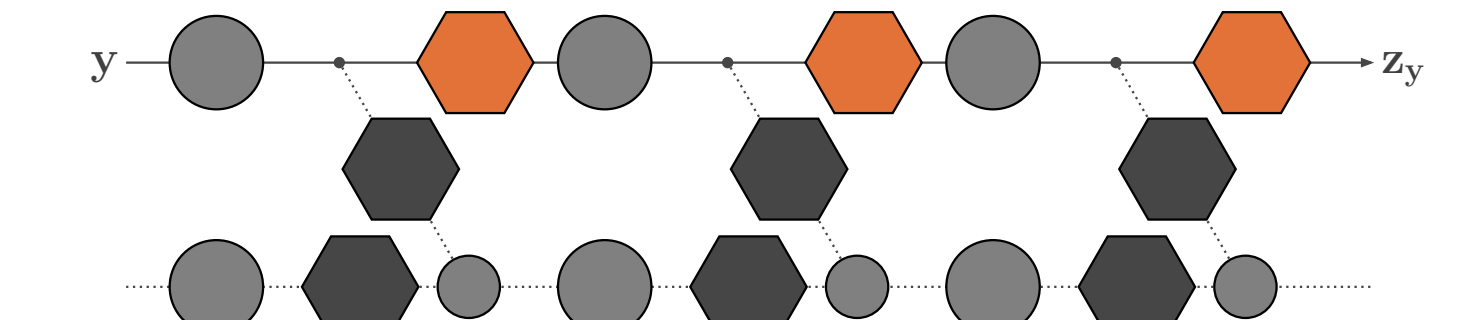
→ ensured by keeping shuffling matrices \mathbf{Q} separate

► **Training** same as before, as one joint network $T(\mathbf{y}, \mathbf{x})$

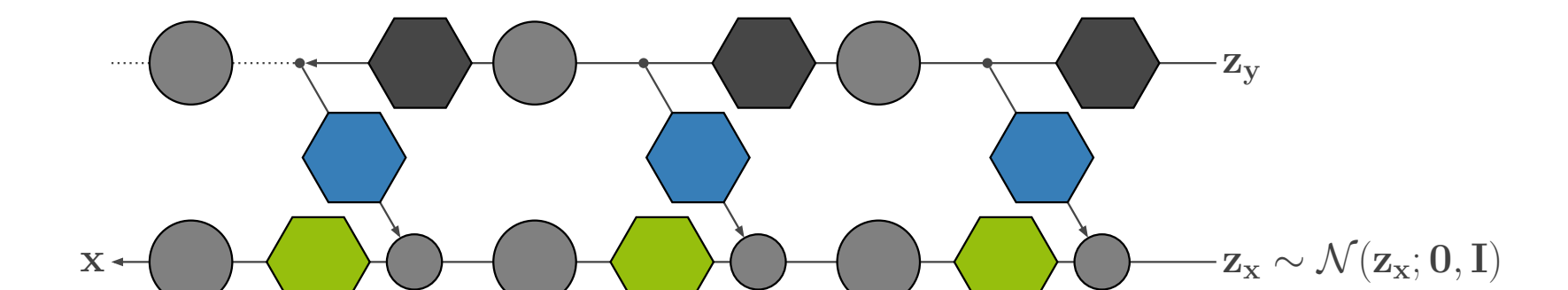


$$\mathcal{L}(\mathbf{y}, \mathbf{x}) = \frac{1}{2} \|\mathbf{T}(\mathbf{y}, \mathbf{x})\|_2^2 - \log |\mathbf{J}_T(\mathbf{y}, \mathbf{x})|$$

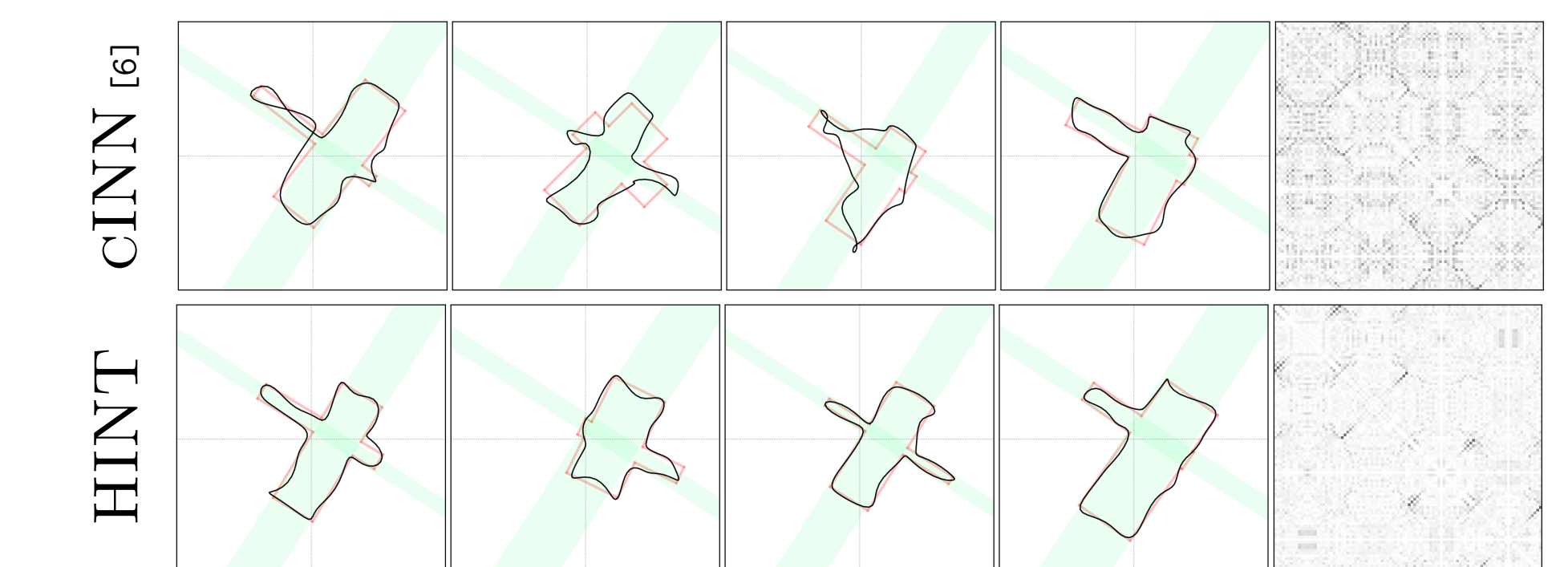
► **Sampling** by first running only \mathbf{y} -lane to get \mathbf{z}_y



then holding \mathbf{z}_y fixed and running inverse with Gaussian \mathbf{z}_x



► **Results On Fourier Curve Data Set** samples \mathbf{x} conditioned on \mathbf{y} = (angle, center, thickness ratio); and corr. matrix errors:



Quantitative results in terms of *log-likelihood*, *intersection-over-union* and average *Hausdorff distance*:

BLOCKS	4x cINN [6]	4x HINT	8x cINN [6]	8x HINT
LL ↑	3.625	3.724	3.609	3.766
IoU ↑	0.654	0.843	0.590	0.859
H-DIST ↓	0.116	0.073	0.119	0.066

→ **Hierarchical transport better in all 3 metrics**

[1] Rezende and Mohamed. **Variational inference with normalizing flows**. ICML 2015.

[2] Dinh et al. **NICE: Non-linear Independent Components Estimation**. ICLR 2015.

[3] Dinh et al. **Density estimation using Real NVP**. ICLR 2017.

[4] Dua and Graff. **UCI Machine Learning Repository**. 2017. <http://archive.ics.uci.edu/ml>.

[5] McGarva and Mullineux. **Harmonic representation of closed curves**. Appl. Math. Model. 1993

[6] Ardizzone et al. **Conditional Invertible Neural Networks for Diverse Image-to-Image Translation**. GCPR 2020.

<CODE>
github.com/VLL-HD/HINT

<DATA SETS>
github.com/VLL-HD/inn_toy_data

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